

Lecture 55: Final Review:

(130)

Reminder: Office Hours, etc on Final Handout.

Differential Forms: Things can be integrated over manifolds of the right dimension. They do this by eating vectors.

[Point: provide a unified approach to integration theorems, which we rather add hoc, because of 3-dimensionality.]

In \mathbb{R}^2 and \mathbb{R}^3 everything we do with forms can also be done with vectorfields, curl, div, etc. Not true in higher dims,

[cross product special to dim 3/4.] and in e.g. special relativity it is best to think of $\vec{E} = (E_1, E_2, E_3)$, $\vec{B} = (B_1, B_2, B_3)$

$$F = E_1 dx \wedge dt + E_2 dy \wedge dt + E_3 dz \wedge dt +$$
$$B_1 dy \wedge dz + B_2 dz \wedge dx + B_3 dx \wedge dy \quad \text{on } \mathbb{R}^4$$

} write up ahead of time.

$J = \rho dt + J_1 dx + J_2 dy + J_3 dz$ (J, J_1, J_2) current density.
(otherwise, figuring out behavior under Lorentz transformations is tricky.)

Maxwell: $dF = 0$ and $d(*F) = 4\pi(*J)$

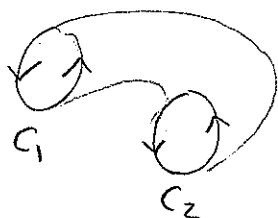
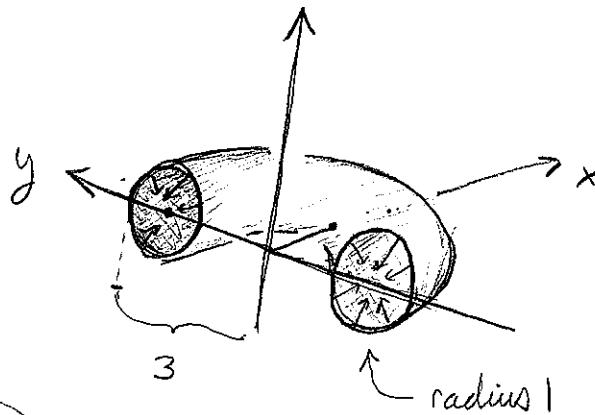
or ... Clearly invariant under L . transforms.

[Even though diff forms on \mathbb{R}^2 and \mathbb{R}^3 are equivalent to things about vectorfield, curl, etc, you may find it easier to just forget this. — the relationship is somewhat convoluted.]

- Main things:
- 1) How to integrate forms..
 - 2) the d operation.
 - 3) Stokes theorem.

Ex: S is

with inward normal



Check Stokes' theorem for

$$\alpha = (x^2 + y) dz$$

$$\int_{\partial S} \alpha = \int_{C_1} \alpha + \int_{C_2} \alpha \quad \text{and we can parametrize these curves as}$$

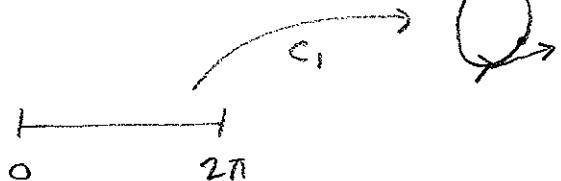
$$c_1(t) = (0, 2 + \cos t, -\sin t)$$

$$c_2(t) = (0, -2 + \cos t, -\sin t)$$

$$0 \leq t \leq 2\pi$$

$$\int_{C_1} \alpha = \int_0^{2\pi} \alpha_{c_1(t)}(c_1'(t)) = \int_0^{2\pi} (\cos t + 2) dz(c_1'(t)) = \int_0^{2\pi} (\cos t + 2) \cos t dt$$

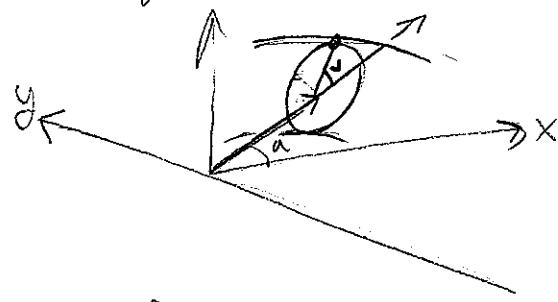
$$= \int_0^{2\pi} -\cos^2 t + 2 \cos t dt = -\pi$$



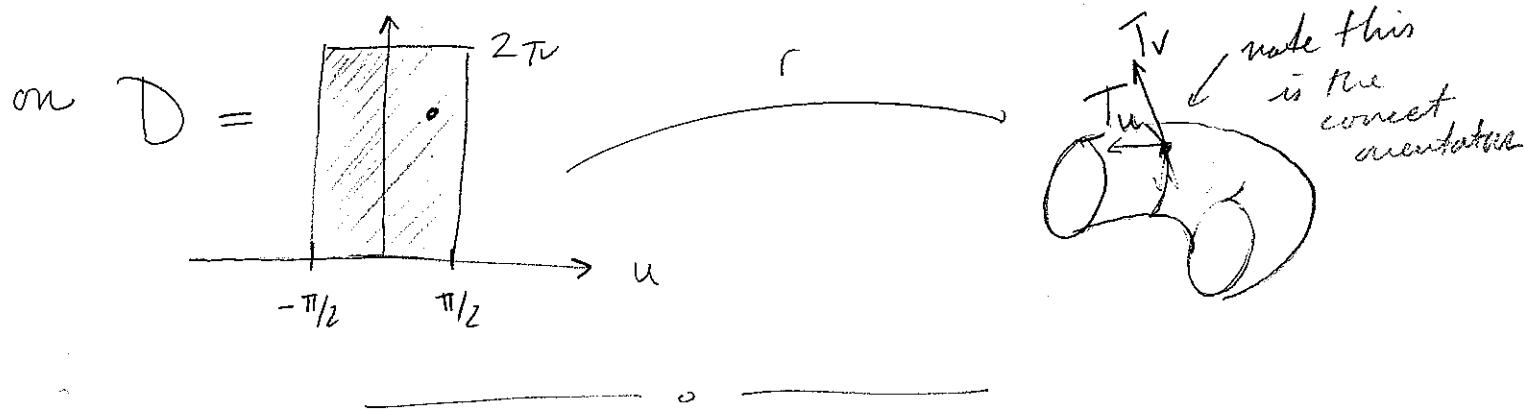
$$\text{Similarly, } \int_{C_2} \alpha = -\pi \text{ and}$$

$$\text{hence } \int_{\partial S} \alpha = -2\pi$$

Now we need to parameterize the surface



$$\begin{aligned} r(u, v) &= \\ &(2 \cos u, 2 \sin u, 0) + \\ &(\cos v \cos u, \cos v \sin u, -\sin v) \\ &= ((2 + \cos v) \cos u, (2 + \cos v) \sin u, -\sin v) \end{aligned}$$



$$d\alpha = d(x^2 y) \wedge dz = (2x dx + dy) \wedge dz = 2x dx \wedge dz + dy \wedge dz$$

and so

$$\begin{aligned} \int_S d\alpha &= \iint_D d\alpha_{r(u,v)}(T_u, T_v) = \int_{-\pi/2}^{\pi/2} \int_0^{2\pi} 2(2 + \cos v) dx \wedge dz(T_u, T_v) \\ &\quad + dy \wedge dz(T_u, T_v) dv du \\ &= \int_{-\pi/2}^{\pi/2} \int_0^{2\pi} 2(2 + \cos v) \begin{vmatrix} dx(T_u) & dx(T_v) \\ dz(T_u) & dz(T_v) \end{vmatrix} + \begin{vmatrix} dy(T_u) & dy(T_v) \\ dz(T_u) & dz(T_v) \end{vmatrix} dr du \end{aligned}$$

$$\text{As } T_u = (- (2 + \cos v) \sin u, (2 + \cos v) \cos u, 0)$$

$$T_v = (-\sin v \cos u, -\sin v \sin u, -\cos v)$$

$$= \int_{-\pi/2}^{\pi/2} \int_0^{2\pi} 2(2 + \cos v) \begin{vmatrix} -(2 + \cos v) \sin u & -\sin v \cos u \\ 0 & -\cos v \end{vmatrix} + \begin{vmatrix} (2 + \cos v) \cos u & -\sin v \sin u \\ 0 & -\cos v \end{vmatrix} dudv$$

$$= \int_{-\pi/2}^{\pi/2} \int_0^{2\pi} + 2(2 + \cos v)^2 \sin u \cos v - (2 + \cos v) \cos v \cos u dv du$$

$$= \int_0^{2\pi} \int_{-\pi/2}^{\pi/2} \text{same } dudv = \int_0^{2\pi} 2(2 \cos v - \cos^2 v) = -2\pi$$

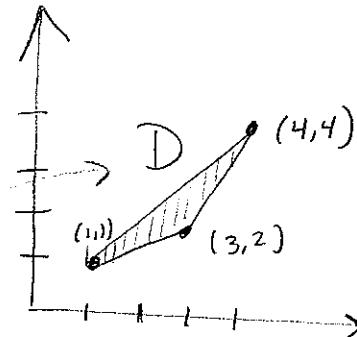
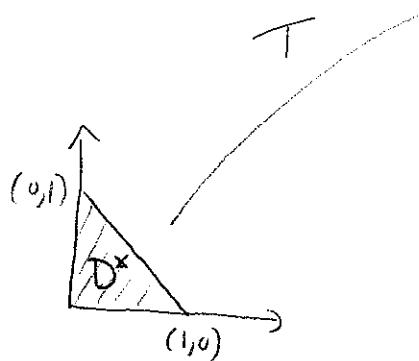
Thus:

$$\int_{\partial S} \alpha = -2\pi = \int_S d\alpha$$

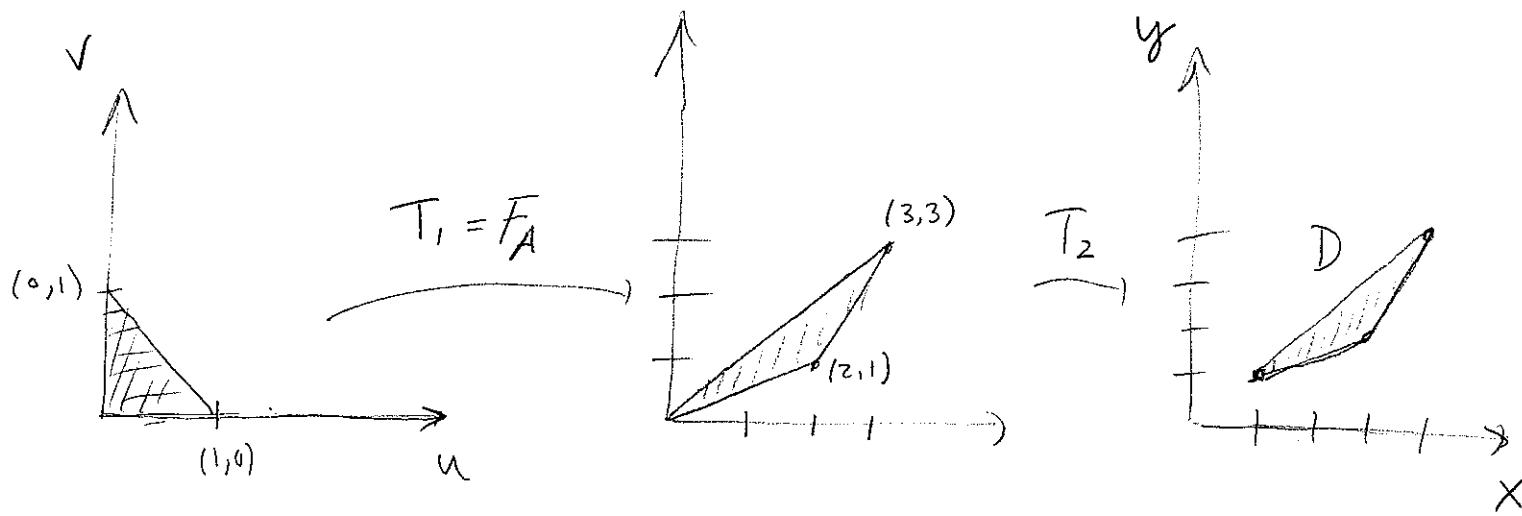
as per Stokes' Theorem!

Change of Variables:

$$\iint_D (x^2 + y^2) dA$$



Favorite kind of T : linear, but that won't work here



$$A = \begin{pmatrix} 2 & 3 \\ 1 & 3 \end{pmatrix}$$

$$T_2(x, y) = (x+1, y+1)$$

$$T_1(u, v) = (2u+3v, u+3v)$$

$$T(u, v) = T_2(T_1(u, v)) = (2u+3v+1, u+3v+1)$$

$$\iint_D x^2 + y^2 dA = \iint_0^1 \int_0^{1-v} ((2u+3v+1)^2 + (u+3v+1)^2) |\det DT(u, v)| du dv$$

Comments on final:

- Comprehensive.
- Problems somewhat harder than previous exam,
but not 3 times as many.
- Same basic format.
- Any questions?