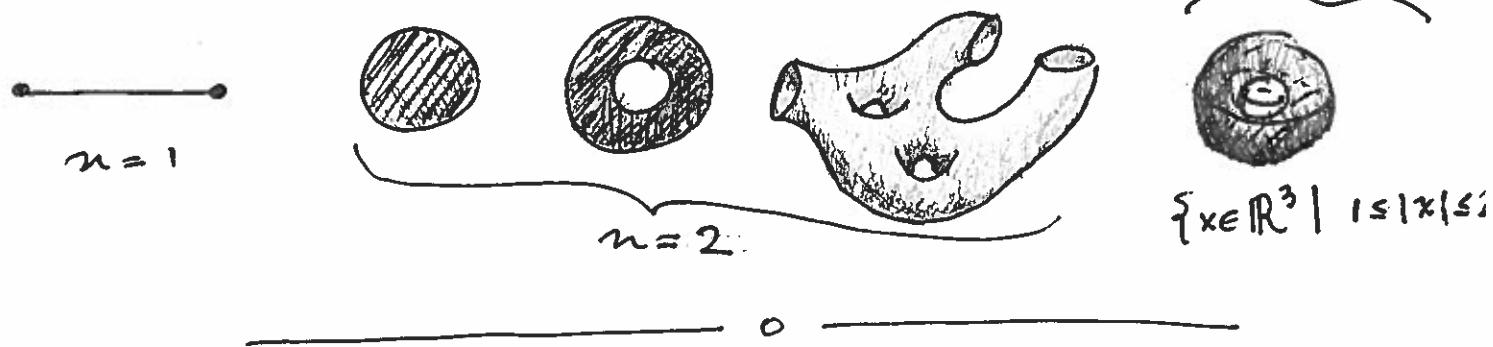


Lecture 33: Proof of Stokes Theorem

①

Stokes Thm: Suppose that M is a smooth oriented n -manifold with boundary. If $\omega \in \Omega^{n-1}(M)$ is compactly supported, then $\int_M d\omega = \int_{\partial M} \omega$.



Pf: Let (U_i, φ_i, ψ_i) be a partition of unity for M
 chart bump fn.

Define $w_i = \psi_i \omega$. Since ω is compactly supported, only finitely many w_i are non-zero.

[This is just local finiteness; only finitely many $\text{supp } \psi_i$ can meet $\overline{\text{supp } \omega}$.]

Say $\omega = \sum_{i=1}^N w_i$. Enough to show $\int_M d\omega_i = \int_{\partial M} w_i$

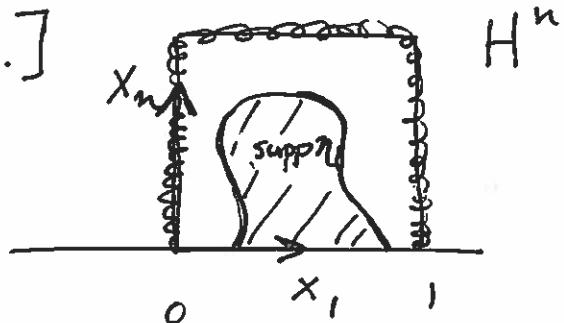
for each i , since then $\int_M d\omega = \int_M d(\sum w_i) =$

$$\int_M \sum d\omega_i = \sum \int_M d\omega_i = \sum \int_{\partial M} w_i = \int_{\partial M} \sum w_i = \int_{\partial M} \omega.$$

Since $\overline{\text{supp } \omega_i} \subseteq U_i$, can compute $\int_M \omega_i$ and $\int_{\partial M} \omega_i$ via the single chart $\varphi_i: U_i \rightarrow \mathbb{R}^n$ or H^n (2)

So we have reduced to the case $M = H^n$, and by changing coordinates we can assume that $\text{supp } \omega \subseteq [0, 1]^n$.

Now $\omega = \sum f_i dx_1 \wedge \dots \wedge \widehat{dx_i} \wedge \dots \wedge dx_n$ and again enough to prove it for each term. Two cases [up to changing coordinates.]



$$\textcircled{A} \quad \eta = f(x) dx_1 \wedge \dots \wedge dx_n$$

Now $\int_{\partial M} \eta = 0$ since $\eta = 0$ when all input vectors are in $T_p \partial M$. Have $d\eta = \frac{\partial f}{\partial x_1}(x) dx_1 \wedge \dots \wedge dx_n$

$$\text{So } \int_M d\eta = \int_0^1 \dots \int_0^1 \frac{\partial f}{\partial x_1}(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n$$

$$= \int_0^1 \dots \int_0^1 f(1, x_2, \dots, x_n) - f(0, x_2, \dots, x_n) dx_2 \dots dx_n$$

$$= 0 \text{ as needed.}$$

(3)

$$\textcircled{B} \quad \eta = f(x) dx_1 \wedge \dots \wedge dx_{n-1}$$

$$\int_{\partial H^n} \eta = (-1)^n \int_0^1 \dots \int_0^1 f(x_1, \dots, x_{n-1}, 0) dx_1 \dots dx_{n-1}$$

because orient on ∂H^n isn't always the same as that on \mathbb{R}^{n-1} .

$$d\eta = (-1)^{n-1} \frac{\partial f}{\partial x_n}(x) dx_1 \wedge \dots \wedge dx_n. \quad \text{So}$$

$$\begin{aligned} \int_{H^n} dw &= \int_0^1 \dots \int_0^1 (-1)^{n-1} \frac{\partial f}{\partial x_n}(x) dx_n dx_1 \dots dx_{n-1} \\ &= (-1)^{n-1} \int_0^1 \dots \int_0^1 f(x_1, \dots, x_{n-1}, 1) - f(x_1, \dots, x_{n-1}, 0) \stackrel{0}{\leftarrow} dx_1 \dots dx_{n-1} \\ &= (-1)^n \int_0^1 \dots \int_0^1 f(x_1, \dots, x_{n-1}, 0) dx_1 \dots dx_{n-1}, \\ &= \int_{\partial H^n} \eta \end{aligned}$$

So we're done!

Q.E.D.

[This proof was fairly easy but somewhat formal.]
 To get more intuition about Stokes theorem,
 let's see what it says for a Riemannian metric...

(4)

(M, g) oriented Riemannian mfld with boundary.

$\omega_g \in \Omega^n(M)$ the volume form.

[Philosophy: a R-metric allows us to go between various kinds of tensors...]

Define

$*: C^\infty(M) \rightarrow \Omega^n(M)$ which is an isomorphism
 $f \longrightarrow f \omega_g$ [Example of Hodge star.]

Note for $f \in C^\infty(M)$ we defined $\int_M f d\text{Vol} = \int_M *f$

Also, have $\beta: \mathcal{X}(M) \rightarrow \Omega^{n-1}(M)$
 $X \rightarrow X \lrcorner \omega_g$

Define the divergence operator $\text{div}: \mathcal{X}(M) \rightarrow C^\infty(M)$
by $\text{div } X = *^{-1}(d(\beta(X)))$

Equivalently

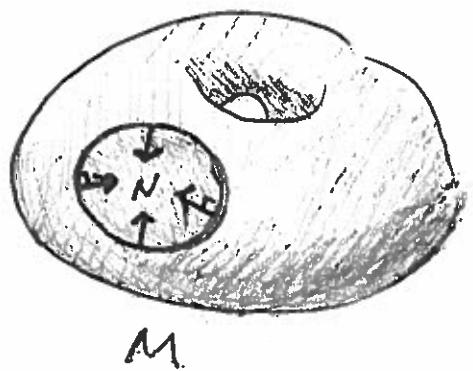
$$(\text{div } X) \omega_g = d(X \lrcorner \omega_g)$$

(5)

Divergence Theorem: (M, g) oriented Riemannian manifold with boundary. If $X \in \mathcal{X}(M)$ is compactly supported, and N is the outward-pointing unit normal vector field on ∂M , then

$$\int_M (\operatorname{div} X) d\operatorname{Vol}_M$$

$$= \int_{\partial M} g(N, X) d\operatorname{Vol}_{\partial M}$$



where the Riemannian metric on ∂M is just the restriction of the one on M .

This has a physical interpretation....