

Integration on Manifolds (Lecture 30)

①

An orientation on M^n is a locally consistent choice of orientation on each $T_p M$; it can be specified by $\omega \in \Omega^n(M)$ where each $\omega_p \neq 0$.

Partition of Unity: Countable (U_i, φ_i, ψ_i) where (U_i, φ_i) are smooth charts, $\psi_i: M \rightarrow [0, 1]$ smooth fns and

- Ⓐ $\text{supp } \psi_i \subseteq U_i$
- Ⓑ Every p is in finitely many $\text{supp } \psi_i$
- Ⓒ $\sum_i \psi_i = 1$.

A form $\omega \in \Omega^n(M)$ is compactly supported if $\text{supp } \omega = \{p \in M \mid \omega_p \neq 0\}$ is contained in a cpt set.

Def: $U \subseteq \mathbb{R}^n$ open. For compactly supported $\omega \in \Omega^n(U)$, write $\omega = f dx_1 \wedge \dots \wedge dx_n$ where $f \in C^\infty(\mathbb{R}^n)$ is 0 outside U . Define

$$\int_U \omega = \int_U f dV = \int_{a_n}^{b_n} \dots \int_{a_1}^{b_1} f(x_1, \dots, x_n) dx_1 \dots dx_n$$

where $\Pi[a_i, b_i]$ is any cpt box containing $\text{supp } f = \text{supp } \omega$.

Suppose M is an oriented n -mfld and $\omega \in \Omega^n(M)$ ⁽²⁾ is compactly supported. Define

$$\int_M \omega = \sum_i \int_{\varphi_i(U_i)} (\varphi_i^{-1})^* (\psi_i \cdot \omega)$$

← Really only a finite sum.

where (U_i, φ_i, ψ_i) is a partition of unity where each φ_i is orientation preserving. [Query: Why can we add the last condition?]

Note: Since $\text{supp } \psi_i \subseteq U_i$, the form $(\varphi_i^{-1})^* (\psi_i \omega)$ is smooth and compactly supported on $\varphi_i(U_i)$.

Thm. $\int_M \omega$ does not depend on the choice of the partition of unity.

Proof: First note that $\int_M \omega$ with respect to some fixed (U_i, φ_i, ψ_i) is linear in ω . Suppose

$(V_j, \bar{\varphi}_j, \bar{\psi}_j)$ is another partition of 1. Consider

$$\omega = \sum_{i,j} \underbrace{(\psi_i \bar{\psi}_j \omega)}_{\eta_{ij}} \quad [\text{which is really a finite sum.}]$$

Now we have $\text{supp } \eta_{ij} \subseteq U_i$ and V_j . By

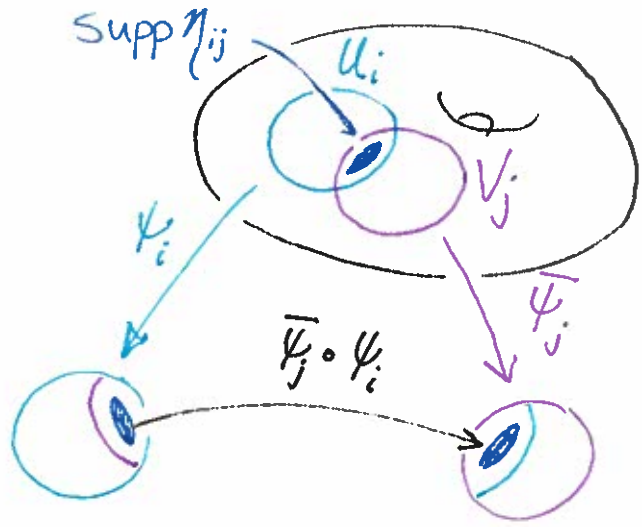
linearity we just need to check $\int_M \eta_{ij}$ is the same in both partitions of unity.

To see this, note

$$(\psi_i^{-1})^*(\eta_{ij})$$

is

$$(\bar{\psi}_j \circ \psi_i)^* \left((\bar{\psi}_j^{-1})^* \eta_{ij} \right)$$



and so the theorem follows from

Lemma: Suppose $F: U \rightarrow V$ is an orient. pres. diffeo of open subsets of \mathbb{R}^n . If $\eta \in \Omega^n(V)$ is compactly supported

then
$$\int_V \eta = \int_U F^* \eta$$

Idea: Write $\eta = f(x) dx_1 \wedge \dots \wedge dx_n$ $f \in C^\infty(V)$

and $F^* \eta = g(x) dx_1 \wedge \dots \wedge dx_n$ $g \in C^\infty(U)$

Have

$$\begin{aligned}
 g(x) &= (F^* \eta) \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \Big|_x \right) \\
 &= \eta_{(F(x))} \left(dF \left(\frac{\partial}{\partial x_1} \Big|_x \right), \dots, dF \left(\frac{\partial}{\partial x_n} \Big|_x \right) \right) \\
 &= f(F(x)) \cdot \det(D_x F)^t = f(F(x)) \det(D_x F)
 \end{aligned}$$

Columns of DF

Since F is orient. pres, $\det(D_x F) > 0$. So lemma is now "just" the change of variables formula for multiple integrals. ▀

Volumes of Riemannian Manifolds:

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M^n oriented with Riemannian metric g .

The volume form $\omega_g \in \Omega^n(M)$ is defined by

$$\omega_g(v_1, \dots, v_n) = \left. \begin{array}{l} \text{signed vol of the} \\ \text{pallelopped spanned} \\ \text{by } v_1, \dots, v_n \in T_p M \\ \text{with respect to } g_p. \end{array} \right\} \Rightarrow \omega_g = 1 \text{ on any pos. oriented orthonormal basis.}$$

More explicitly

$$\omega_g(v_1, \dots, v_n) = \sqrt{\det(g_p(v_i, v_j))}$$

if (v_1, \dots, v_n) are a pos. oriented basis.

Reason this is the right formula: On \mathbb{R}^n with g_{DOT} ,

given (v_1, \dots, v_n) consider the matrix $A = \begin{pmatrix} -v_1- \\ \vdots \\ -v_n- \end{pmatrix}$

$$\begin{aligned} \text{Then } \det(g_{\text{DOT}}(v_i, v_j)) &= \det(AA^t) = (\det A)^2 \\ &= (\text{sign vol span } v_i)^2. \end{aligned}$$

For $f \in C^\infty(M)$ can now define $\int_M f dV$

$$\text{as } \int_M f \omega_g.$$