

Lecture 31: Exterior Differentiation

(1)

$$\Omega^k(M) = \left\{ \begin{array}{l} \text{smooth } k\text{-forms} \\ p \mapsto \Lambda^k(T_p M) \end{array} \right\}$$

Goal: Define $d: \Omega^k(M) \rightarrow \Omega^{k+1}(M)$

generalizing $C^\infty(M) \rightarrow \Omega^1(M)$. Note that
 $f \mapsto df$

by definition $\Lambda^0 V = \mathbb{R}$, so $C^\infty(M) = \Omega^0(M)$.

Exterior Algebra: $\Lambda(V) = \bigoplus_{k=0}^{\dim V} \Lambda^k V$

Operations are addition and \wedge product, which make it an associative graded (anti) commutative algebra:

$$\alpha \wedge \beta = (-1)^{kl} \beta \wedge \alpha \quad \alpha \in \Lambda^k V, \beta \in \Lambda^l V$$

Algebra of differential forms: $\Omega(M) = \bigoplus_{k=0}^{\dim M} \Omega^k(M)$

Thm: M a smooth mfld, poss. with boundary. There are unique maps $d: \underbrace{\Omega^k(M)}_{\text{exterior derivatives}} \rightarrow \Omega^{k+1}(M)$ satisfying

(a) d is linear over \mathbb{R} .

(b) $\omega \in \Omega^k(M)$ and $\eta \in \Omega^l(M)$ then

$$d(\omega \wedge \eta) = d\omega \wedge \eta + (-1)^k \omega \wedge d\eta$$

(c) $d \circ d = 0$

(d) For $f \in \Omega^0(M)$, df is the usual differential of f , i.e. $df(v_p) = v_p f$.

Some observations:

(1) Anything satisfying (b) and (d) must be local, i.e. $(d\eta)_p$ is determined by $\eta|_U$ for any $p \in U \subseteq M$.

Reason: Take ψ with $\overline{\text{supp } \psi} \subseteq U$ and $\psi = 1$ on $p \in V \subseteq U$

Then $d(\psi \wedge \eta) = d\psi \wedge \eta + \psi \cdot d\eta$

is just $d\eta$ on V and $\text{supp}(\psi \eta) \subseteq U$.

[Thus should be able to compute in local coord.]

② On \mathbb{R}^n these props completely det $d\omega$. For example, ③

$$d(dx_{i_1} \wedge \dots \wedge dx_{i_k}) = 0 \quad \text{since } d(dx_{i_j}) = 0$$

where here $x_i: \mathbb{R}^n \rightarrow \mathbb{R}$

and so if $\omega \in \Omega^2(\mathbb{R}^3)$ is

$$\omega = (x+z^2) dx \wedge dy + e^y dx \wedge dz$$

then $d\omega = \underbrace{d(x+z^2)}_{dx+2zdz} \wedge dx \wedge dy + \underbrace{d(e^y)}_{e^y dy} \wedge dx \wedge dz$

$$= 2z dz \wedge dx \wedge dy + e^y dy \wedge dx \wedge dz$$

$$= (2z - e^y) dx \wedge dy \wedge dz.$$

Two approaches to proving Thm:

① Show well-defined for $\Omega^*(\mathbb{R}^n)$

Show that for $F: U \rightarrow V$ a diffeomorphism we have $F^*(d\omega) = d(F^*\omega)$.

Define d on M via charts. This ↖ fact gives that it is well defined.

See text for details.

(B) Coordinate-free definition: $\omega \in \Omega^1(M)$

Define $d\omega \in \Omega^2(M)$ by the property that if $X, Y \in \mathcal{X}(M)$ then

$$d\omega(X, Y) = \underbrace{X(\omega(Y)) - Y(\omega(X)) - \omega([X, Y])}_{f_{X, Y} \in C^\infty(M)}$$

Note clear antisymmetry, bilinearity

Claim: $f_{X, Y}(p)$ only depends on X_p and Y_p .

Idea: Enough to show $f_{\psi X, \psi Y} = \psi f_{X, Y}$, which is an easy calculation.

In general, for $\omega \in \Omega^k(M)$ define

$$d\omega(X_0, X_1, \dots, X_k) = \sum_{i=0}^k (-1)^i X_i(\omega(X_1, \dots, \hat{X}_i, \dots, X_k)) + \sum_{0 \leq i < j \leq k} (-1)^{i+j} \omega([X_i, X_j], X_0, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_k)$$

means remove

For details on (A) and (B), see Lee.

<p><u>Prop</u>: $F: M \rightarrow N$ $\omega \in \Omega^k(N)$. Then $d(F^*\omega) = F^*(d\omega)$</p>
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Lie derivatives of differential forms: $V \in \mathfrak{X}(M)$,

$\omega \in \Omega^k(M)$. Define $\mathcal{L}_V \omega \in \Omega^k(M)$ by

$$(\mathcal{L}_V \omega)_p = \left. \frac{d}{dt} \right|_{t=0} (\Theta_t^* \omega)_p$$

where Θ is the flow assoc to V . in $\Lambda^k T_p M$

Alternatively, using the same ideas as the proof that $L_X Y = [X, Y]$ it follows that for any $X_1, \dots, X_k \in \mathfrak{X}(M)$

$$\begin{aligned} \mathcal{L}_V \omega(X_1, \dots, X_k) &= V(\omega(X_1, \dots, X_k)) - \omega([V, X_1], X_2, \dots, X_k) \\ &\quad - \dots - \omega(X_1, X_2, \dots, [V, X_k]) \end{aligned}$$

Prop: $V \in \mathfrak{X}(M)$ and $\omega, \eta \in \Omega^*(M)$, then

$$\mathcal{L}_V(\omega \wedge \eta) = (\mathcal{L}_V \omega) \wedge \eta + \omega \wedge (\mathcal{L}_V \eta)$$

Cartan's Magic Formula: $\mathcal{L}_V \omega = V \lrcorner (d\omega) + d(V \lrcorner \omega)$

Here, the interior product $V \lrcorner \omega$ is the $k-1$ form

$$\text{defined by } (V \lrcorner \omega)(\underbrace{W_1, \dots, W_{k-1}}_{\in T_p M}) = \omega(V_p, W_1, \dots, W_{k-1})$$