

# Lecture 25: More Riemannian Geometry

①

Riemannian metric: Smooth choice of  $g_p: T_p M \times T_p M \rightarrow \mathbb{R}$ ,  
a symmetric positive definite bilinear form, for each  $p \in M$ .

Lengths:  $\gamma: [a, b] \rightarrow M$  curve  $L(\gamma) = \int_a^b \underbrace{|\gamma'(t)|}_{\parallel \sqrt{g_{\gamma(t)}(\gamma'(t), \gamma'(t))}} dt$

Distances:

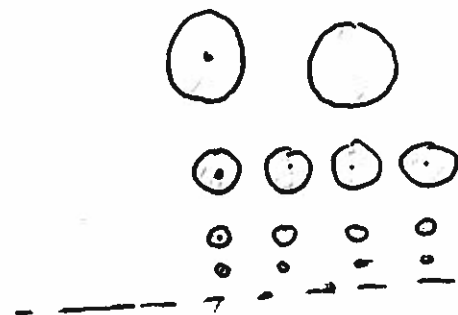
$$d(p, q) = \inf \left\{ L(\gamma) \mid \begin{array}{l} \gamma \text{ a curve from} \\ p \text{ to } q \end{array} \right\}$$

Tensor product:  $\alpha, \beta \in V^*$  define the bilinear form

$$\alpha \otimes \beta: V \times V \rightarrow \mathbb{R} \text{ by } \alpha \otimes \beta(x, y) = \alpha(x) \beta(y)$$

Examples: ①  $\mathbb{H}^2 = \text{hyperbolic plane} = \{(x, y) \in \mathbb{R}^2 \mid y > 0\}$

$$g_{(x, y)} = \frac{1}{y^2} \underbrace{(dx \otimes dx + dy \otimes dy)}_{\text{Euclidean dot product}}$$

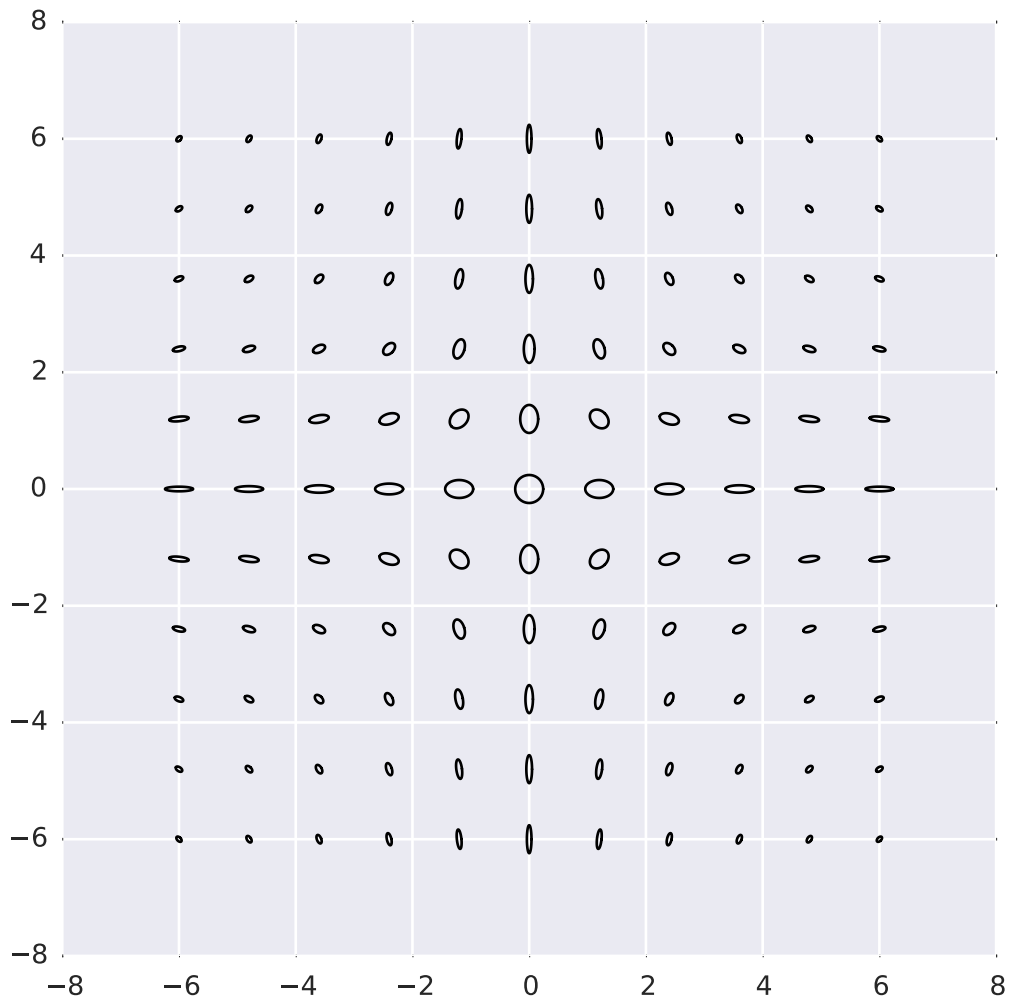


$$C_p = \{v \in T_p \mathbb{H}^2 \mid g_{(x, y)}(v, v) = 1\}$$

②  $g_{(x, y)} = (1+x^2) dx \otimes dx + \frac{xy}{2} (dx \otimes dy + dy \otimes dx)$

$$M = \mathbb{R}^2 \quad + (1+y^2) dy \otimes dy$$

[Show picture on next page]



Remark on smoothness: A vector field  $p \mapsto X_p \in T_p M$  is smooth if any of the following equivalent conditions hold:

(a)  $X: M \rightarrow TM$  is smooth, where  $TM$  has a particular smooth str.

(b)  $\forall$  smooth charts  $(U, \varphi)$  we have

$$\hat{X} = \sum X_i \frac{\partial}{\partial x_i} \quad \text{where } X_i \in C^\infty(\varphi(U))$$

(c)  $\forall f \in C^\infty(M)$  the function  $Xf: M \rightarrow \mathbb{R}$  is smooth. [c  $\Rightarrow$  b:  $X_i = X x_i$ ]

Same 3 conditions make sense for Riemannian metrics.

$$(b) \hat{g}_{(x_1, \dots, x_n)} = \sum_{i,j} \overbrace{g_{ij}(x_1, \dots, x_n)}^{\text{smooth}} dx_i \otimes dx_j$$

(c) ~~the~~  $\forall X, Y \in \mathcal{X}(M)$  the fun ~~g(X, Y) \in C^\infty(M)~~  
 $p \mapsto g_p(X_p, Y_p)$  is smooth.

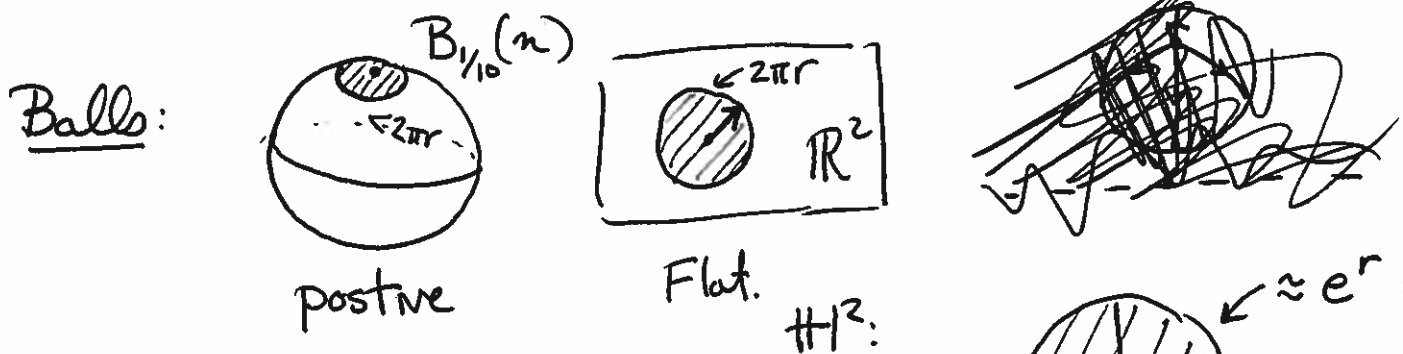
[ (a) Also makes sense, one has a vector bundle over  $M$  with fibers  $BF(T_p M)$  but will not focus on this for now. ]

[More geometry...] Thm: Every smooth  $M^n$  has a Riem. metric. (3)

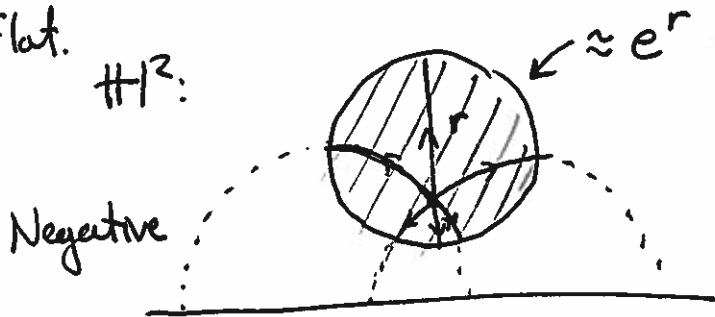
Geodesics: A curve  $\gamma$  from  $a$  to  $b$  is a geodesic if  $L(\gamma) = d(a, b)$ . [Really should say locally...]



Volumes: Will discuss soon.



Curvature:



$K_p$  is defined by [not that 2<sup>nd</sup> fundamental form!]

$$\text{length}(\partial B_r(p)) = 2\pi r - \frac{\pi}{3} K(p) r^3 + \text{lower order terms.}$$

Key feature: A Riemannian metric relates  $TM \leftrightarrow T^*M$  (4)

Algebra:  $V$  vector space. A bilinear form  $g: V \times V \rightarrow \mathbb{R}$  is non-degenerate if  $\forall x \in V \exists y, y' \in V$  with  $g(x, y) \neq 0$  and  $g(y', x) \neq 0$ .

Example:  $g$  positive definite.

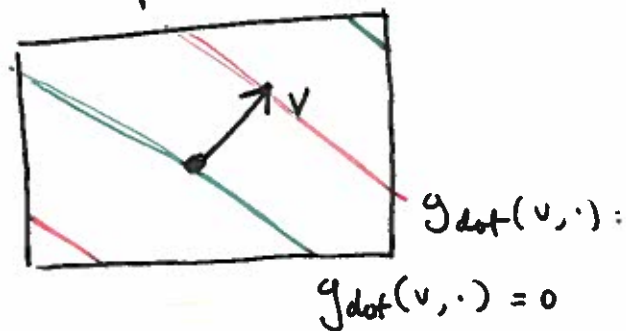
~~Define~~ A bilinear form  $g$  gives a map  $V \rightarrow V^*$  by  $v \mapsto (w \mapsto g(v, w))$   
 $g(v, \cdot)$

Thm: If  $V$  is finite dim'l and  $g$  non-degenerate then  $v \mapsto g(v, \cdot)$  is an isomorphism.

Ex:  $T_p \mathbb{R}^n$ ,  $g_{\text{dot}}$

$\frac{\partial}{\partial x_i}$  basis.

$g_{\text{dot}}(\frac{\partial}{\partial x_i}, \cdot) \in T_p^* \mathbb{R}^n$  is just  $dx_i$ .



So, if  $g$  is an Riem. metric on  $M$ , get

$$\begin{aligned} TM &\xrightarrow{\cong} T^*M \\ v_p &\longmapsto g_p(v_p, \cdot) \end{aligned}$$

and hence  $\mathcal{X}(M) \longleftrightarrow \Omega^1(M)$

$$X \longmapsto X^b$$

$$\omega^\# \longleftarrow \omega$$

Recall  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  have  $df \in \Omega^1(\mathbb{R}^n)$  given by

$$df = \frac{\partial f}{\partial x_1} dx_1 + \dots + \frac{\partial f}{\partial x_n} dx_n$$

which is  $\left( \text{grad } f = \frac{\partial f}{\partial x_1} \frac{\partial}{\partial x_1} + \dots + \frac{\partial f}{\partial x_n} \frac{\partial}{\partial x_n} \right)^b$ .

For  $f \in C^\infty(M)$  where  $M$  is Riemannian, we

~~get~~ define  $\text{grad } f \in \mathcal{X}(M)$  as  $(df)^\#$ .

[It has all the usual properties....]

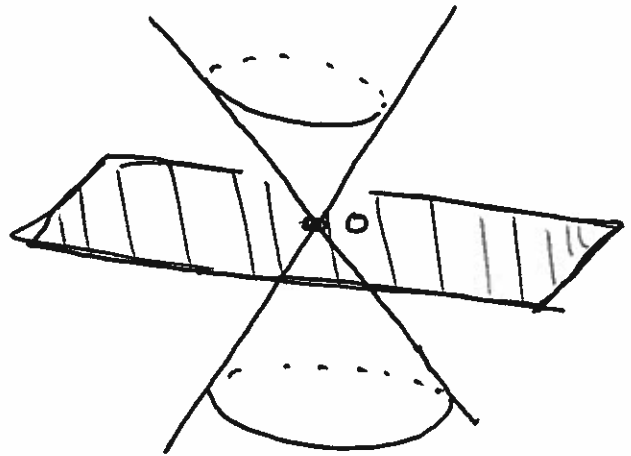
Pseudo-Riemannian:  $g_p$  nondegen sym. bilinear form  
on  $T_p M$ .

(6)

Lorentzian:  $g((x_1, x_2, x_3), (y_1, y_2, y_3))$

$$= x_1 y_1 + x_2 y_2 - x_3 y_3$$

~~$g(x, x)$~~   
 $g(x, x) = 0$  lightlike  
 $> 0$  spacelike  
 $< 0$  timelike



Lorentzian mfd: A form of this type at  
each  $p \in M$ . The basic object in general  
relativity.

[If time remains, do hyperboloid model of  $\mathbb{H}^2$ .]