

Lecture 13: Lie Groups

Vector fields: $(p \in M) \mapsto X_p \in T_p M$ [Section of the tangent bundle.]
 $\mathcal{X}(M) = \{\text{smooth vector fields}\}$

[Originated in study of sym. of diff eqns, but now...]

Lie group: A smooth mfd G which is also a group and where

$$m: G \times G \rightarrow G \quad \text{and} \quad i: G \rightarrow G$$

$$(g, h) \mapsto g \cdot h \quad \text{and} \quad g \mapsto g^{-1}$$

are both smooth.

Ex: ① $(\mathbb{R}^n, +)$ $m(v, w) = v + w$ $i(v) = -v$

② $(\mathbb{R}^x = \mathbb{R} - \{0\}, \cdot)$

③ $GL_n(\mathbb{R}) = \underbrace{\{A \in M_n(\mathbb{R}) \mid \det A \neq 0\}}_{\substack{\text{open hence a mfd of} \\ \text{dim } n^2}} \subseteq \mathbb{R}^{n^2}$

$m =$ matrix multiplication

$n=2:$

$$\left. \begin{aligned} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} a' & b' \\ c' & d' \end{pmatrix} &= \begin{pmatrix} aa'+bc' & \cdot \\ \cdot & \cdot \end{pmatrix} \\ i \begin{pmatrix} a & b \\ c & d \end{pmatrix} &= \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} \end{aligned} \right\} \text{Both smooth}$$

[How are these different than $(\mathbb{R}^n, +)$? What is $GL_1(\mathbb{R})$.]

④ $O(n) = \{A \in M_n(\mathbb{R}) \mid A \cdot A^t = I\}$
 $U(n) = \{A \in M_n(\mathbb{C}) \mid A \cdot \bar{A}^t = I\}$
 $SL_n \mathbb{R} = \{A \in M_n(\mathbb{R}) \mid \det A = 1\}$ } - skim

⑤ $S^1 \subseteq \mathbb{C}$ under multiplication, $(\omega), \dots$

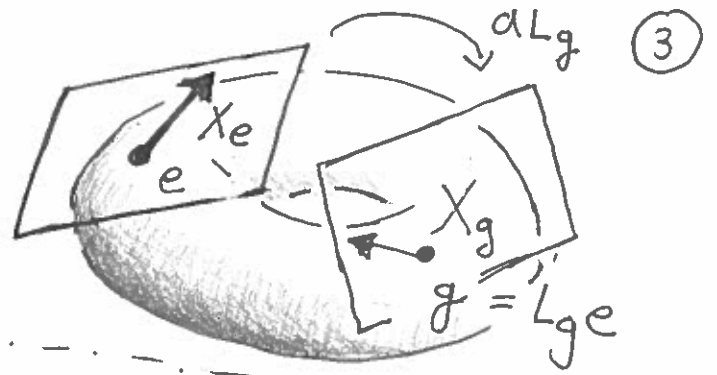
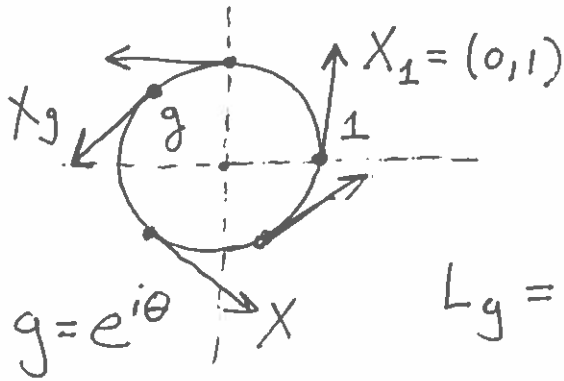
For fixed $g \in G$ consider the maps $G \rightarrow G$ given by $L_g: h \mapsto gh$ and $R_g: h \mapsto hg$
 left translation right translation

These are smooth and in fact diffeomorphisms (inverses are $L_{g^{-1}}$ and $R_{g^{-1}}$ respectively.)

Note $L_{g_2} \circ L_{g_1} = L_{g_2 g_1}$ and $R_{g_1} \circ R_{g_2} = R_{g_2 g_1}$

Consider $X_e \in T_e G$. Define a vector field on G by $X_g = (dL_g)(X_e)$.
 ↑ ident. elt.

Ex. $G = S^1$



$L_g = R_g =$ counter-clockwise rotation through angle θ .

Lemma: Let G be a Lie group, and choose $X_e \in T_e G$.
The vector field $g \mapsto X_g = (d(L_g))(X_e)$ is smooth.

Proof: Let $\gamma: I \rightarrow G$ be a path with $\gamma'(0) = X_e$.

Then $X_g = d(L_g)(X_e) = (L_g \circ \gamma)'(0) = (g \cdot \gamma)'(0)$.

Now consider $(0, X_e) \in T_g G \times T_e G = T_{(g, e)} G \times G$

which is the velocity vector of $\alpha(t) = (g, \gamma(t))$
at $t=0$. Note that

$$\begin{aligned} dm_{(g, e)}(0, X_e) &= (m \circ \alpha)'(0) = (g \cdot \gamma)'(0) \\ &= X_g \end{aligned}$$

Smoothness of X follows from smoothness of

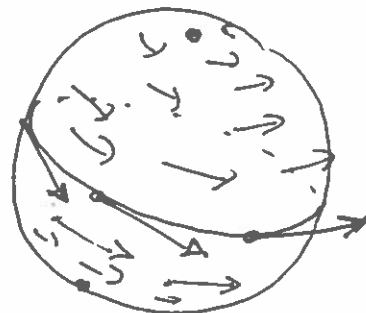
$$dm: T(G \times G) \rightarrow TG.$$



(4)

Note that if $X_e \neq 0$ so is $d(L_g)(X_e) = X_g$.

That is, G has a smooth nowhere vanishing vector field. (Fact: S^2 can't be made into a Lie group!)



Cor. If G is a Lie gp of dim n , then $TG \cong G \times \mathbb{R}^n$.

Sketch: Let X_e^1, \dots, X_e^n be basis for $T_e G$. Define vector fields X^k by $X_g^k = dL_g(X_e^k)$. Then

$$\begin{aligned} G \times \mathbb{R}^n &\longrightarrow TG \\ (g, (t_1, \dots, t_n)) &\longmapsto \sum_{k=1}^n t_k X_g^k \in T_g G \end{aligned}$$

is a diffeomorphism.

Suppose $F: M \rightarrow N$ is a diffeomorphism. ⑤

For $X \in \mathcal{X}(M)$ the push-forward $F_* X \in \mathcal{X}(N)$

$$\begin{aligned} \text{is given by } (F_* X)_g &= dF_{F^{-1}(g)}(X_{F^{-1}(g)}) \\ &= (dF^{-1})_g^{-1}(X_{F^{-1}(g)}) \end{aligned}$$

A vector field $X \in \mathcal{X}(G) \stackrel{\text{Lie } \mathfrak{g}}{\leftarrow}$ is left invariant if $(L_g)_* X = X$ for all $g \in G$.

Note that if X is left-invariant then

$$X_g = ((L_g)_* X)_g = (dL_g)_e X_e \underset{\uparrow (L_g)^{-1}(g)}{\quad}$$

which is the vector field we defined above. In fact, any such vector field is left invariant.

Cor: $\{X \in \mathcal{X}(G) \mid \text{left-invariant}\} \cong T_e G$

Lie Algebra.