

Lecture 39: Dealing with nondiagonalizable matrices. ①

(§6.7 and §7.1)

Last time: For a linear op T on a finite dim'l inner product space V , the following are equivalent:

- 1) T is an isometry, i.e. $\langle T(x), T(y) \rangle = \langle x, y \rangle$ for all $x, y \in V$.
- 2) $T \circ T^* = T^* \circ T = I_V$
- 3-4) For every (some) orthonormal basis β for V , the image $T(\beta)$ is an orthonormal basis.
- 5) $\|T(x)\| = \|x\|$ for all $x \in V$.

Def: A square matrix is unitary when $A^*A = I$ and orthogonal when $A^t A = I$.

[With respect to an orthonormal basis, an isometry has a unitary (and orthogonal if $\mathbb{F} = \mathbb{R}$) matrix.]

Thm: Suppose $A \in M_{n \times n}(\mathbb{R})$ is orthogonal. Then L_A is an isometry of $(\mathbb{R}^n, \text{dot})$.

Pf: Set $a_i = Ae_i = i^{\text{th}}$ col of A . Then $I =$

$$A^t A = \begin{pmatrix} - & a_1 & - \\ \vdots & \vdots & \vdots \\ - & a_n & - \end{pmatrix} \begin{pmatrix} | & | & | \\ a_1 & \dots & a_n \\ | & | & | \end{pmatrix} = G \text{ where } G_{ij} = \langle a_i, a_j \rangle$$

In particular $\{L_A(e_i)\}$ is an orthonormal basis of \mathbb{R}^n .

Cor: $A \in M_{n \times n}(R)$. TFAE:

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- i) A is orthogonal
 - ii) $A^t = A^{-1}$
 - iii) the columns of A are an orthonormal basis for \mathbb{R}^n .
 - iv) — rows —
 - v) L_A is an isometry of $(\mathbb{R}^n, \text{dot})$.

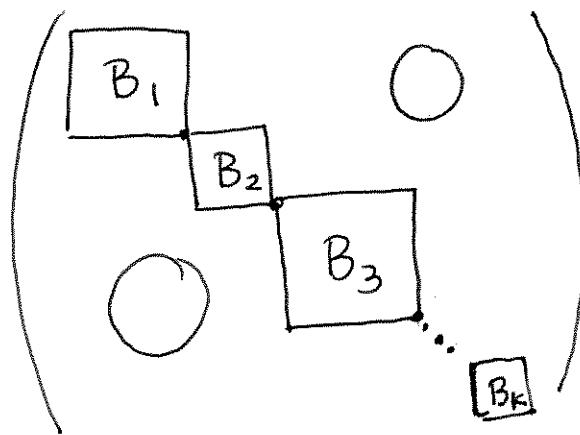
Pf: Exercise.

Restated Thm: Suppose $A \in M_{n \times n}(\mathbb{R})$ is symmetric.

Then there is an orthogonal Q with $Q^t A Q = Q^{-1} A Q$ diagonal.

What to do when $A \in M_{n \times n}(\mathbb{R})$ is not diagonalizable?

Jordan Canonical Form: Over \mathbb{C} , any square matrix is similar to one of the following form:



where each block
has the form

$$\begin{pmatrix} x_i & 1 & 0 \\ x_i & ! & 0 \\ 0 & \ddots & x_i & 1 \\ & & & x_i \end{pmatrix}$$

Ex:

$$A = \begin{pmatrix} & & & \\ & \boxed{\begin{matrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{matrix}} & & \\ & & \boxed{2} & \\ & & & \boxed{\begin{matrix} 3 & 1 \\ 0 & 3 \end{matrix}} \\ & & & & \boxed{5} \\ & & & & \boxed{\begin{matrix} 0 & 1 \\ 0 & 0 \end{matrix}} \\ & & & & \\ & & & & \end{pmatrix}$$

$$\begin{aligned} E_2 &= \text{span}(\{e_1, e_4\}) \\ E_3 &= \text{span}(\{e_5\}) \\ E_5 &= \text{span}(\{e_7\}) \\ E_0 &= \text{span}(\{e_8\}) \end{aligned}$$

Remarks: Suppose A is in Jordan Can. Form.

- 1) The λ_i are the eigenvalues of A .
- 2) For each block, the e_i cor. to the first column is an eigenvector for A . In fact,
 $\dim(E_\lambda) = \# \text{ of blocks assoc to } \lambda$.
- 3) Can still understand powers: (see page 519 for details)

$$A^n = \begin{pmatrix} & & & \\ & \boxed{\begin{matrix} 2^n & n2^{n-1} & \frac{n(n-1)}{2}2^{n-2} \\ 0 & 2^n & n2^{n-1} \\ 0 & 0 & 2^n \end{matrix}} & & \\ & & \boxed{2^n} & \\ & & & \boxed{\begin{matrix} 3^n & n3^{n-1} \\ 0 & 3^n \end{matrix}} \\ & & & & \boxed{5^n} \\ & & & & \boxed{\begin{matrix} 0 & 0 \\ 0 & 0 \end{matrix}} \\ & & & & \\ & & & & \end{pmatrix}$$

for $n > 1$.

Applications:

1) Proof that any regular Markov chain converges.

Point: Blocks B with $|\lambda| < 1$ have $\lim_{n \rightarrow \infty} B^n = 0$.

2) Solving systems of linear differential equations.

Singular Value Decomposition: Work over \mathbb{R} for concreteness.

Story so far: $T: V \xrightarrow{\text{linear}} V \iff A = [T]_{\beta} \in M_{n \times n}(\mathbb{R})$

Goal: Choose β so that

$[T]_{\beta}$ is simple $\iff B = Q^{-1}AQ$
 as possible. \uparrow diagonal, J.C.F., etc.

Problems: 1) To use J.C.F. need to work over \mathbb{C} .

2) What about $T: V \rightarrow W$?

In (2), there's not even any notion of an eigenvector! However we do get to choose two bases, β for V and γ for W , in order to write down $[T]_{\beta}^{\gamma}$. [This gives more flexibility]

(5)

even if $W = V$ since $[T]_{\beta} = [T]_{\beta}^{\beta}$.]

Thm [Probably Skip!] Suppose $T: V \rightarrow W$ is linear and V and W are finite dim'l. Then there are

bases so that $[T]_{\beta}^{\gamma} = \begin{pmatrix} I_0 & \\ 0 & \ddots & 0 \\ \vdots & \ddots & \ddots \\ 0 & 0 & \ddots \end{pmatrix}$.

$\underbrace{\quad}_{\text{rank}(T)} \underbrace{\quad}_{\text{nullity}(T)}$

Pf (Skip!): Using the rep'l. theorem, pick a basis $\beta = \{v_1, \dots, v_n\}$ whose last k vectors are a basis for $N(T)$. Again via replacement, extend $\{T(v_1), \dots, T(v_{n-k})\}$ (which is linearly independent) to a basis γ for W . Then $[T]_{\beta}^{\gamma}$ has the desired form. \blacksquare

Singular Value Decomposition: Suppose T is a linear map between real inner product spaces V and W . Then there exist orthonormal

basis β and γ so that

$$[T]_{\beta}^{\gamma} = \begin{pmatrix} \sigma_1 & 0 & & & 0 \\ 0 & \sigma_2 & & & \\ & & \ddots & & 0 \\ & & & \ddots & 0 \\ 0 & & & & 0 \end{pmatrix}$$

where $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r \geq 0$ are in \mathbb{R} . (6)

Notes: 1) Here $r = \text{rank}(T)$.

2) It turns out ^{that} the singular values σ_i are unique.

3) Matrix form: Given $A \in M_{m \times n}(\mathbb{R})$ there exist $P \in M_{m \times m}(\mathbb{R})$ and $Q \in M_{n \times n}(\mathbb{R})$, both orthonormal, so that PAQ has the above form. (Like diagonalizing a symmetric matrix, except we do not insist that $P = Q^t = Q^{-1}$.)

Proof idea for SVD: Diagonalize $T^* \circ T$.

[Only talked about T^* for linear ops, not general linear transformations, so just think about the case when $W = V$.]

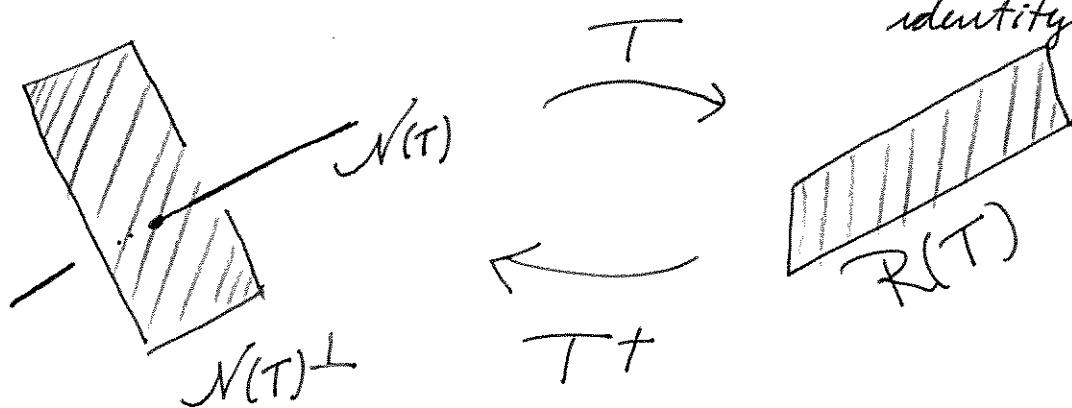
Applications:

1) Pseudo-inverse: Given $T: V \rightarrow W$

there is a $T^t: W \rightarrow V$ where

(7)

$T^+(W) = \mathcal{N}(T)^\perp$, the linear op $T \circ T^+$ is orthogonal projection onto $\mathcal{R}(T)$, and $T^+ \circ T$ is the identity on $\mathcal{N}(T)^\perp$.



Point: The restriction $L : \mathcal{N}(T)^\perp \rightarrow \mathcal{R}(T)$
 $x \mapsto T(x)$

is an isomorphism, and $T^+ = L^{-1} \circ \text{proj}_{\mathcal{R}(T)}$

2) Computing determinants. When A is square and invertible, $\det(A) = \pm \sigma_1 \cdots \sigma_r$

Proof: By HW, $\det(\text{orthogonal}) = \pm 1$.

3) In fact, the SVD has been a key tool in scientific computing for 50+ years.